- The inverse of a ITI system, if such a system exists, is a ITI system.
- Let h and h_{inv} denote the impulse responses of a ITI system and its (ITI) inverse, respectively. Then:

$$h * h_{inv} = \delta.$$

• Consequently, a ITI system with impulse response h is invertible if and only if there exists a function h_{nv} such that

$$h * h_{inv} = \delta$$
.

• Except in simple cases, the above condition is often quite difficult to test.

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• A ITI system with impulse response *h* is BIBO stable if and only if $\sum_{\infty=1}^{\infty} h(t) | dt \infty > t$

)i.e., *h* is *absolutely integrable*.(

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• An input x to a system H is said to be an eigenfunction of the system H with the eigenvalue λ if the corresponding output y is of the form

where λ is a complex constant.

- In other words, the system H acts as an ideal amplifier for each of its eigenfunctions X, where the amplifier gain is given by the corresponding eigenvalue λ .
- Different systems have different eigenfunctions.
- Of particular interest are the eigenfunctions of ITI systems.

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- As it turns out, every complex exponential is an eigenfunction of all ITI systems.
- For a ITI system H with impulse response h

$$H\{e^{st}\} = H(s)e^{st}$$

where \boldsymbol{S} is a complex constant and

$$H(s) = (\sum_{\infty}^{\infty} h(t) e^{-st} dt.$$

- That is, e^{st} is an eigenfunction of a ITI system and H(s) is the corresponding eigenvalue.
- We refer to *H* as the system function (or transfer function) of the system *H*.
- From above, we can see that the response of a ITI system to a complex exponential is the same complex exponential multiplied by the complex factor H(s(

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- Consider a ITI system with input X, output Y, and system function H.
- Suppose that the input X can be expressed as the linear combination of complex exponentials

$$x(t) = \sum_{k} a_{k} e^{s_{k} t_{k}}$$

where the A_k and S_k are complex constants.

Using the fact that complex exponentials are eigenfunctions of ITI systems, we can conclude

$$y(t) = \sum_{k} a_{k} H(s_{k}) e^{s_{k}t}.$$

- Thus, if an input to a LTI system can be expressed as a linear combination of complex exponentials, the output can also be expressed as a linear combination of the *same* complex exponentials.
- The above formula can be used to determine the output of a ITI system from its input in a way that does not require convolution.

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Part 4

Continuous - Time Fourier Series (CTFS)

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- The Fourier series is a representation for *periodic* signals.
- With a Fourier series, a signal is represented as a *linear combination of complex sinusoids*.
- The use of complex sinusoids is desirable due to their numerous attractive properties.
- For example, complex sinusoids are continuous and differentiable. They are also easy to integrate and differentiate.
- Perhaps, most importantly, complex sinusoids are *eigenfunctions* of ITI systems.

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Section 4.1

Fourier Series

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- A set of complex sinusoids is said to be harmonically related if there exists some constant ω_0 such that the fundamental frequency of each complex sinusoid is an integer multiple of $\omega_{.0}$
- Consider the set of harmonically-related complex sinusoids given by

- The fundamental frequency of the *k*th complex sinusoid φ_k is $k\omega_0$, an integer multiple of ω_0 .
- Since the fundamental frequency of each of the harmonically-related complex sinusoids is an integer multiple of ω_0 , a linear combination of these complex sinusoids must be periodic.
- More specifically, a linear combination of these complex sinusoids is periodic with period $T = 2\pi / \omega_0$.

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• A periodic complex signal X with fundamental period T and fundamental frequency $\omega_0 = \frac{2\pi}{T}$ can be represented as a linear combination of harmonically-related complex sinusoids as

$$X(t) = \sum_{k^{\infty}=1}^{\infty} C_k e^{ik\omega_0 t}.$$

- Such a representation is known as (the complex exponential form of) a (CT) Fourier series, and the C_k are called Fourier series coefficients.
- The above formula for X is often referred to as the Fourier series synthesis equation.
- The terms in the summation for k = K and k = -K are called the Kth harmonic components, and have the fundamental frequency $K\omega_{.0}$
- To denote that a signal X has the Fourier series coefficient sequence C_k , we write

$$X(t) \xleftarrow{}{} CTFS C_k$$

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• The periodic signal X with fundamental period T and fundamental frequency $\omega_0 = \frac{2\pi}{T}$ has the Fourier series coefficients C_k given by

$$C_{k} = \frac{\frac{1}{T}}{\tau} \int_{\tau}^{T} x(t) e^{-jk\omega_{0}t} dt,$$

where ${}^{t}_{T}$ denotes integration over an arbitrary interval of length T (i.e., one period of λ).

• The above equation for C_k is often referred to as the Fourier series analysis equation.

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- Consider the periodic signal X with the Fourier series coefficients C_k . If
- X is real, then its Fourier series can be rewritten in two other forms, known as the combined trigonometric and trigonometric forms.
- The combined trigonometric form of a Fourier series has the appearance

$$x(t) = c_0 + 2\sum_{k=1}^{\infty} |c_k| \cos(k\omega_0 t + \theta_k),$$

where $\theta_k = \arg C_k$.

• The trigonometric form of a Fourier series has the appearance

$$x(t) = a_0 + \sum_{k=1}^{\infty} \left[\alpha_k \cos k \omega_0 t + \beta_k \sin k \omega_0 t \right],$$

where $\alpha_k = 2 \operatorname{Re} C_k$ and $\beta_k = -2 \operatorname{Im} C_k$.

Note that the trigonometric forms contain only *real* quantities.

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Section 4.2

Convergence Properties of Fourier Series

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- Since a Fourier series can have an infinite number of terms, and an infinite sum may or may not converge, we need to consider the issue of convergence.
- That is, when we claim that a periodic signal X(t) is equal to the Fourier series $\sum_{k=-\infty}^{\infty} C_k \Theta^{ik\omega_0 t}$, is this claim actually correct?
- Consider a periodic signal X that we wish to represent with the Fourier series

$$\sum_{k^{\infty}=1}^{\infty} C_k e^{ik\omega_0 t}.$$

• Let X_W denote the Fourier series truncated after the Nth harmonic components as given by

$$x_{N}(t=(\sum_{k=-N}^{N}C_{k}\Theta^{jk\omega_{0}t})$$

• Here, we are interested in whether $\lim_{N\to\infty} X_N(t)$ is equal (in some sense) to x(t).

• The *error* in approximating x(t) by $x_{N}(t)$ is given by

$$e_{\mathcal{N}}(t) = x(t) - x_{\mathcal{N}}(t),$$

and the corresponding *mean-squared error (MSE)* (i.e., energy of the error) is given by

$$E_{\mathcal{N}} = \frac{\frac{1}{T}}{T} \frac{1}{\tau} |e_{\mathcal{N}}(t)|^2 dt.$$

- If $\lim_{N\to\infty} e_N(t) = 0$ for all t (i.e., the error goes to zero at every point), the Fourier series is said to converge pointwise to x(t).
- If convergence is pointwise and the rate of convergence is the same everywhere, the convergence is said to be uniform.
- If $\lim_{N\to\infty} E_N = 0$ (i.e., the energy of the error goes to zero), the Fourier series is said to converge to X in the MSE sense.
- Pointwise convergence implies MSE convergence, but the converse is not true. Thus, pointwise convergence is a much stronger condition than MSE convergence.